

# The Beris-Edwards system for nematic liquid crystal flows

**Zhewen Feng**  
**(Joint work with Min-Chun Hong and Yu Mei)**

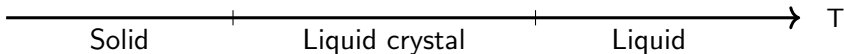
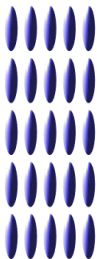
School of Mathematics and Physics  
The University of Queensland

2023

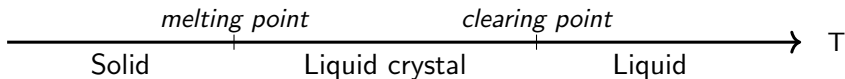
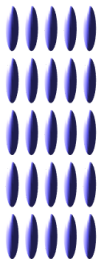
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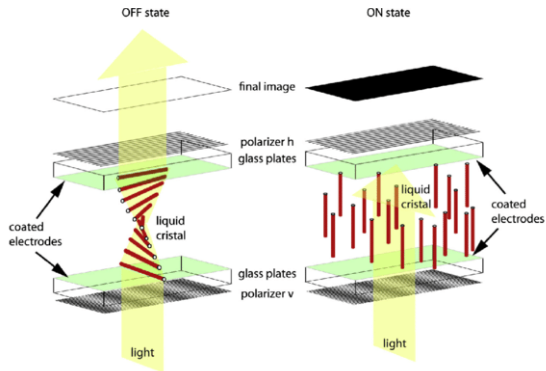
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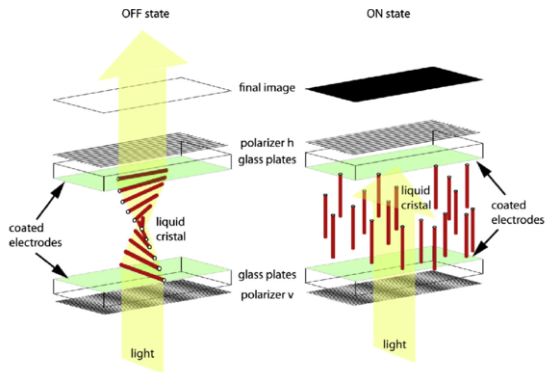


# Applications of the anisotropic property



*Xiao, et al. (2011). Displays. 32. 17-23.*

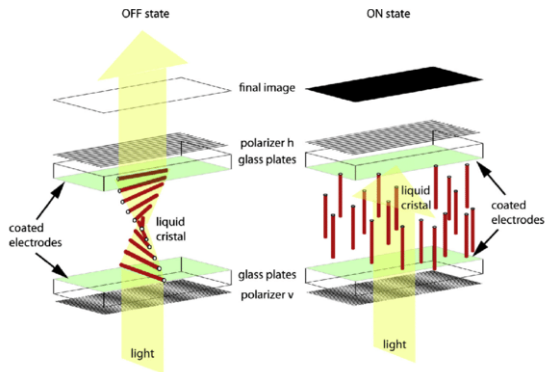
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Leslie explored the theoretical aspects for naturally **twisted** nematics.

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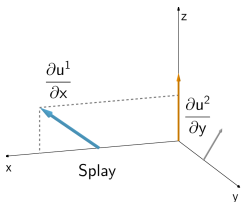
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In 1970, Schadt and Helfrich discovered TN-effect for LCDs.

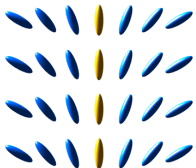


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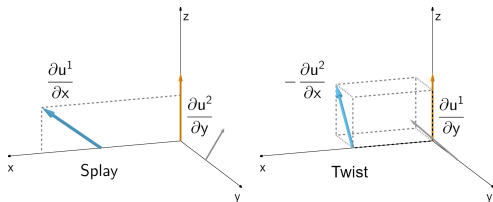
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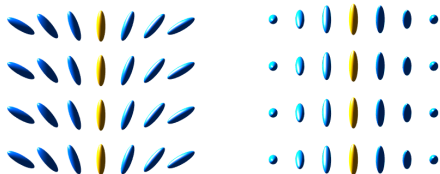
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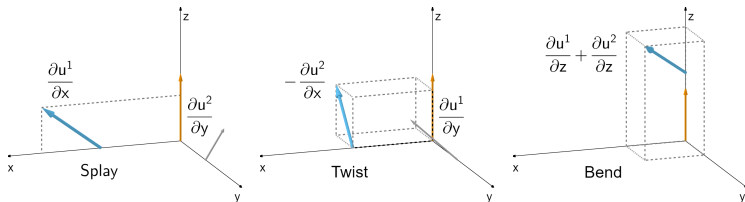
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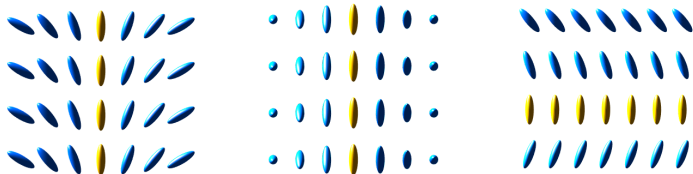
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- ▶ The energy is frame-indifference and rotational invariant.
- ▶ For  $u = (0, 0, 1)$  at the origin, we have a vector notation on the molecular orientations, for instance,

the splay type:  $\frac{\partial u^1}{\partial x} + \frac{\partial u^2}{\partial y} = \operatorname{div} u.$

# The Oseen–Frank energy

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- ▶ The coordinate free form of the energy density is

$$\begin{aligned} W(u, \nabla u) &= k_1(\operatorname{div} u)^2 + k_2(u \cdot \operatorname{curl} u)^2 \\ &\quad + k_3|u \times \operatorname{curl} u|^2 + (k_2 + k_4)[\operatorname{tr}(\nabla u)^2 - (\operatorname{div} u)^2] \end{aligned}$$

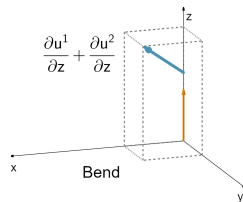
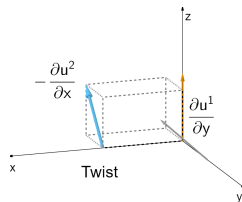
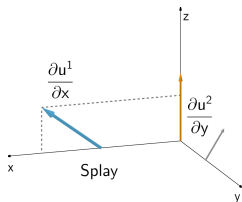
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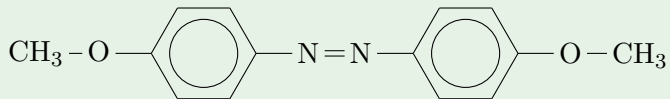
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 W(u, \nabla u) = & \overbrace{k_1 (\operatorname{div} u)^2}^{\text{Splay}} + \overbrace{k_2 (u \cdot \operatorname{curl} u)^2}^{\text{Twist}} \\
 & + \overbrace{k_3 |u \times \operatorname{curl} u|^2}^{\text{Bend}} + \overbrace{(k_2 + k_4) [\operatorname{tr}(\nabla u)^2 - (\operatorname{div} u)^2]}^{\text{Surface energy}}
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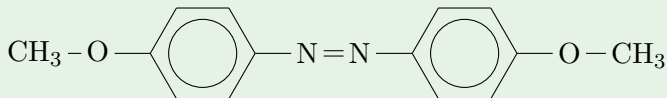
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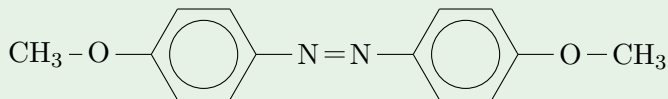
at 125 degrees Celsius has

$$k_1 = 9, \quad k_2 = 5.8 \quad \text{and} \quad k_3 = 19 \quad (\text{unit: } 10^{-12} \text{ Newtons})$$

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Hardt–Kinderlehrer–Lin (CMP, '86) proved that a minimizer  $u$  of the energy  $E(u)$  is **smooth away from a closed set**  $\Sigma \subset \Omega$  which has Hausdorff dimension strictly less than one (the set  $\Sigma$  may not be finite).

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## The Ericksen–Leslie system (ELS)

$$\partial_t v^i + v^j \nabla_j v^i + \nabla_i P - \Delta v = \nabla_j \sigma^E_{ij}$$

$$\nabla_j v^j = 0$$

$$\partial_t u^i + v^j \nabla_j u^i = (\delta_{ik} - u^i u^k) (\nabla_j W_{p_j^k}(u, \nabla u) - W_{u^k}(u, \nabla u))$$

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- ▶ Physics background for ELS: conservation laws for linear momentum, mass and angular momentum respectively.

# The Dirichlet energy

The one-constant model (OCM):  $W(u, \nabla u) \equiv |\nabla u|^2$ .

$$\begin{aligned}\partial_t v^i + v^j \nabla_j v^i + \nabla_i P &= \Delta v^i - \nabla_j (\nabla_i u^k \nabla_j u^k) \\ \nabla_j v^j &= 0 \\ \partial_t u^i + v^j \nabla_j u &= \Delta u^i + |\nabla u|^2 u^i\end{aligned}$$

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- ▶ Such method was initially appeared in the study the phase transition in superconductivity in the 50's.

- The main idea is to **relax the constrain**

$$u \in S^2 \Rightarrow u_\varepsilon \in \mathbb{R}^3,$$

at the cost of a penalized energy

$$E(u) = \int_{\Omega} |\nabla u|^2 dx \Rightarrow E(u_\varepsilon) = \int_{\Omega} |\nabla u_\varepsilon|^2 + \frac{(1 - |u_\varepsilon|^2)^2}{2\varepsilon^2} dx.$$

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### The Ginzburg–Landau system (OCM case)

$$\partial_t v_\varepsilon^i + v_\varepsilon^j \nabla_j v_\varepsilon^i + \nabla_i P_\varepsilon = \nabla v_\varepsilon^i - \nabla_j (\nabla_i u_\varepsilon^k \nabla_j u_\varepsilon^k)$$

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## The Lin-Liu problem

Does  $(u_\varepsilon, v_\varepsilon)$  converge to functions that solve ELS as  $\varepsilon \rightarrow 0$ ?

Significant research and study have been dedicated to the topic of convergence:

- ▶ Lin-Liu (ARMA '00)
- ▶ Hong (CVPDE '10)
- ▶ Hong-Xin (Adv Math '12)
- ▶ Hong-Li-Xin (CPDE '14)
- ▶ F.-Hong-Mei (SIAM Math Anal '20)

This problem provides further motivation for the generalisation of the ELS, which is known as the Beris-Edwards system.

## Some background for the Beris-Edwards system

The most general elastic theory for nematics, which describes all reorientation types, is

the Landau-de Gennes theory.

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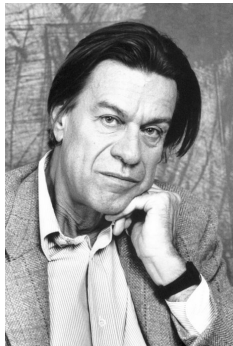


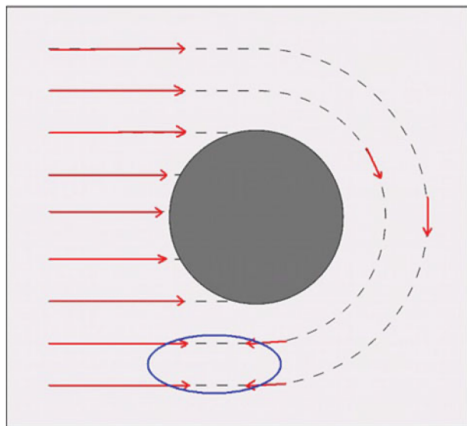
Photo from the Nobel  
Foundation archive

The most general elastic theory for nematics, which describes all reorientation types, is

the Landau-de Gennes theory.

Pierre-Gilles de Gennes was awarded a Nobel prize for physics in 1991 for his work on liquid crystals and polymers.

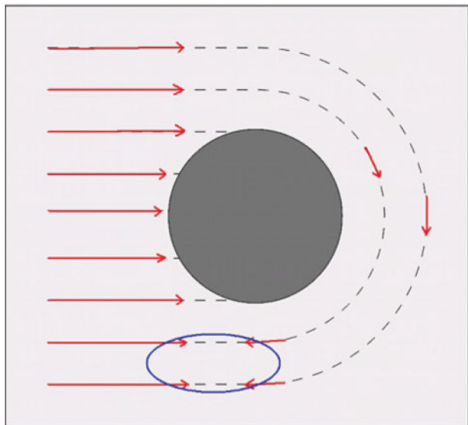
# A problem for vector representation in $S^2$



*Non-simply-connected domains (Ball '17)*

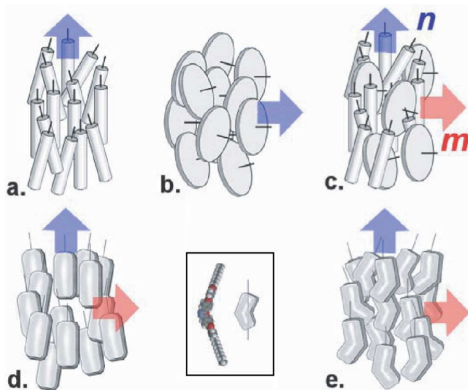
## A problem for vector representation in $S^2$

The Landau-de Gennes model is a tensor representation.  
(isomorphic to the projective plane  $\mathbb{R}P^2$  up to a scaling)



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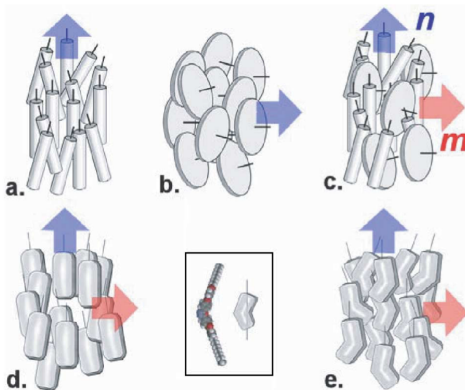
# Biaxial substances for nematics



*Madsen et al. '04.*

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The Landau-de Gennes model works for both uniaxials and biaxials.



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# The Landau-de Gennes Energy

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$$S_0 = \{Q \in \mathbb{M}^{3 \times 3}; Q_{ij} = Q_{ji}, Q_{ii} = 0\}.$$



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- ▶ For  $Q \in W^{1,2}(\Omega; S_0)$ , the Landau-de Gennes energy

$$E_{LG}(Q; \Omega) = \int_{\Omega} f_E(Q, \nabla Q) + f_B(Q) dx.$$

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- ▶ Landau's expansion for phase transitions

$$f_B(Q) = -\frac{a}{2} \text{tr}(Q^2) - \frac{b}{3} \text{tr}(Q^3) + \frac{c}{4} [\text{tr}(Q^2)]^2, \quad a, b, c > 0.$$

## Extension to the Landau-de Gennes energy density

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- ▶ Longa et al. '87, Ball-Majumdar '10 and Golovaty et al. '20 pointed out the  $L_4$  term is problematic.

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### An example from Ball-Majumdar '10

$$Q(x) = \eta(|x|) \left( \frac{x}{|x|} \otimes \frac{x}{|x|} - \frac{1}{3} I \right), \eta(1) = 0, x \in B(0, 1).$$

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The energy density can be arbitrarily large and negative.

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- ▶ Existence of minimizers cannot be guaranteed.

For uniaxial Q-tensors

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We suggest a **new representation**

F.-Hong (CVPDE '22)

$$f_E(Q, \nabla Q) = \left( \frac{L_1}{2} - \frac{s_+ L_4}{3} \right) |\nabla Q|^2 + \frac{L_2}{2} \frac{\partial Q_{ij}}{\partial x_j} \frac{\partial Q_{ik}}{\partial x_k} \\ + \frac{L_3}{2} \frac{\partial Q_{ik}}{\partial x_j} \frac{\partial Q_{ij}}{\partial x_k} + \frac{3L_4}{2s_+} Q_{ln} Q_{kn} \frac{\partial Q_{ij}}{\partial x_l} \frac{\partial Q_{ij}}{\partial x_k}.$$

# Existence of minimizers through scaling analysis

In the case  $L_2 = L_3 = L_4 = 0$ , Majumdar-Zarnescu (ARMA '10) introduced a rescaled energy:

$$\int_{\Omega} \frac{1}{2} |\nabla Q_L|^2 + \frac{\tilde{f}_B(Q_L)}{L} dx,$$

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**Relevance in Physics:** the constant  $L$  is small  $\sim 10^{-11} J \setminus M$ .

The limit  $L \rightarrow 0$  is analogous to the Ginzburg–Landau functional.

In the spirit of Majumdar-Zarnescu's work, we suggest a rescaled Landau-de Gennes energy:

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# The hydrodynamic flow for liquid crystals

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The Beris-Edwards system for uniaxial  $Q \in S_*$

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- ▶  $H(Q, \nabla Q)$  is the first variation for  $Q \in S_*$
- ▶  $\sigma$  is a distortion stress tensor
- ▶  $[\cdot, \cdot]$  is the Lie bracket

## A scaling analysis

- ▶ Recall the rescaled Landau-de Gennes energy

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- ▶ Gartland (MMA '18): This scaling analysis is analogous to
  - "London limit" in the Ginzburg-Landau theory of superconductivity
  - "large-body limit" in the Landau-Lifshitz theory of ferromagnetism

## F.-Hong (CVPDE '22)

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- For the initial condition

$$(Q_0, v_0) \in H_{Q_e}^2(\mathbb{R}^3; S_*) \times H^1(\mathbb{R}^3; \mathbb{R}^3), \operatorname{div} v_0 = 0,$$

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- ▶ Moreover, for any  $T < T^*$ , we prove that

$$(\nabla Q_L, v_L) \rightarrow (\nabla Q, v) \text{ in } C^\infty(\tau, T; C_{loc}^\infty(\mathbb{R}^3)) \text{ for any } \tau > 0.$$



# Ideas from ELS

- ▶ Recall the first variation in ELS:

$$\nabla_{\alpha} W_{p_{\alpha}^i}(u_{\varepsilon}, \nabla u_{\varepsilon}) - W_{u^i}(u_{\varepsilon}, \nabla u_{\varepsilon}) + \frac{u_{\varepsilon}^i(1 - |u_{\varepsilon}|^2)}{\varepsilon^2}.$$

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$$\begin{aligned} & - \int_{\mathbb{R}^3} \Delta u_{\varepsilon}^i \frac{u_{\varepsilon}^i(1 - |u_{\varepsilon}|^2)}{\varepsilon^2} dx \\ & \leq \int_{\mathbb{R}^3} C |\nabla u_{\varepsilon}|^2 \frac{(1 - |u_{\varepsilon}|^2)}{\varepsilon^2} - \frac{1}{4} \frac{|\nabla(|u_{\varepsilon}|^2)|^2}{\varepsilon^2} dx \\ & \leq \int_{\mathbb{R}^3} -\frac{1}{4} \frac{|\nabla(|u_{\varepsilon}|^2)|^2}{\varepsilon^2} + \eta \frac{|1 - |u_{\varepsilon}|^2|^2}{\varepsilon^4} + C(\eta) |\nabla u_{\varepsilon}|^4 dx \end{aligned}$$

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- ▶ The first variation in BES:

$$\mathcal{H}(Q_L, \nabla Q_L) + \frac{1}{L} g_B(Q_L), \quad g_B(Q_L) := \frac{\delta f_B(Q_L)}{\delta Q_L}$$

$$\text{with } f_B(Q_L) = -\frac{a}{2} \text{tr}(Q_L^2) - \frac{b}{3} \text{tr}(Q_L^3) + \frac{c}{4} [\text{tr}(Q_L^2)]^2.$$

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- ▶ The substitution technique does not apply for

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$$S_\delta := \{Q \in S_0 : \text{dist}(Q; S_*) \leq \delta\}.$$

- ▶ For each smooth  $Q \in S_\delta$ , the nearest point projection  $\pi(Q) \in S_*$  has a constant number of distinct eigenvalues, so there exists a smooth rotation  $R_Q := R(\pi(Q)) \in SO(3)$  (Nomizu '73) such that



$$R_Q^T \pi(Q) R_Q = \begin{pmatrix} \frac{-s_+}{3} & 0 & 0 \\ 0 & \frac{-s_+}{3} & 0 \\ 0 & 0 & \frac{2s_+}{3} \end{pmatrix} =: Q^+.$$



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- ▶ F.-Hong-Mei: The Hessian of the bulk density  $f_B$  satisfies

$$\lambda |\xi|^2 \leq \partial_{\tilde{Q}_{ij} \tilde{Q}_{kl}}^2 f_B(Q^+) \xi_{ij} \xi_{kl}, \text{ for some } \lambda > 0.$$

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$$\begin{aligned} & \left\langle \frac{1}{L} \nabla g_B(\tilde{Q}_L), \nabla \tilde{Q}_L \right\rangle \\ & \geq \frac{\lambda}{2} \frac{|\nabla(Q_L - \pi(Q_L))|^2}{L} - C |\nabla Q_L|^2 \frac{|Q_L - \pi(Q_L)|^2}{L}. \end{aligned}$$

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- ▶ A local  $L^3$  criteria

$$\sup_{t, x_0} \int_{B_{R_0}(x_0)} |\nabla Q|^3 + \left| \frac{Q - \pi(Q)}{L^{\frac{1}{2}}} \right|^3 dx \leq \varepsilon_0^3.$$

► Assume that  $(Q_{L,T_0}, v_{L,T_0})$  satisfies

$$\|Q_{L,T_0}\|_{H^2_{Q_e}(\mathbb{R}^3)}^2 + \|v_{L,T_0}\|_{H^1(\mathbb{R}^3)}^2 + \frac{\|Q_{L,T_0} - \pi(Q_{L,T_0})\|_{H^1(\mathbb{R}^3)}^2}{L} \leq M.$$

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- ▶ The Gagliardo–Nirenberg interpolation:

$$\begin{aligned} & \|Q_L - \pi(Q_L)\|_{L^\infty(\mathbb{R}^3)} \\ & \leq C \|Q_L - \pi(Q_L)\|_{L^2(\mathbb{R}^3)}^{\frac{1}{4}} \|\nabla^2(Q_L - \pi(Q_L))\|_{L^2(\mathbb{R}^3)}^{\frac{3}{4}} \leq \frac{\delta}{2}, \end{aligned}$$

and

$$\begin{aligned} \sup_{t, x_0} \int_{B_{R_0}(x_0)} |\nabla Q_L|^3 dx & \leq C \sup_{t, x_0} \left( \frac{1}{R_0} \int_{B_{R_0}(x_0)} |\nabla Q_L|^2 dx \right)^{3/2} \\ & + C \sup_{t, x_0} \left( R_0 \int_{B_{R_0}(x_0)} |\nabla^2 Q_L|^2 dx \right)^{3/2} \leq \frac{\varepsilon_0^3}{2} \end{aligned}$$

for sufficiently small  $L$  and some uniform constants  $T, R_0$  in  $L$ .

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- ▶ We show the existence of a unique strong solution to the Beris-Edwards system up to some  $T$ .
- ▶ For  $T < T^*$  (maximal time), we use the extension technique from Hong-Li-Xin '14 (using the local  $L^3$  criteria).
- ▶ Prove inductively on an estimate of the form

$$\nabla Q \in L^2(\tau, T_M; H^{k+1}(\mathbb{R}^3)), \quad \forall \tau > 0, k \geq 2.$$

- ▶ Prove the convergence up to a uniform short time  $T_M$  and extend the result to maximal time  $T^*$ .